## FP93 <br> Program Controller Instruction Manual

Thank you for purchasing a Shimaden product. Please check that the delivered product is the correct item you ordered. Please do not begin operating this product before you read this instruction manual thoroughly and understand its contents.

## "Notice"

Please ensure that this instruction manual is given to the final user of the instrument.

## "Preface"

This instruction manual is meant for those who will be involved in the wiring, installation, operation and routine maintenance of the FP93. It describes matters to be attended to in handling the FP93, how to install it, wiring, its functions and operating procedure. Keep this manual at the work site while handling the instrument and follow the guidance provided herein.

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## 1. Safety Rules

For matters regarding safety, potential damage to equipment and/or facilities, additional instructions and notes are indicated by the following headings.

## WARNING

This heading indicates hazardous conditions that could cause injury or death of personnel unless extreme caution is exercised.

## CAUTION

This heading indicates hazardous conditions that could cause damage to equipment and/or facilities unless extreme caution is exercised.

## Note

This heading indicates additional instructions and/or notes.
The mark $1 \xlongequal{( })$ represents a protective conductor terminal. Make sure to ground it properly.

## $\triangle$ WARNING

The FP93 Program Controller are control instruments designed for industrial use to control temperature, humidity and other physical values. Avoid using it for control of devices which may seriously affect the human life. When used, adequate and effective safety measures must be taken. No warranty is valid in the case of an accident arising from the use of this product without such safety measures.

## WARNING

- For using this instrument, house it in a control box or the like lest terminals should be in contact with a person.
- Don't draw out the instrument from the case. Don't let your hand or a conductive body in the case. It may lead to serious injury or death due to an electric shock.
- Make sure to ground protective conductor terminals.


## $\triangle$ CAUTION

- To avoid damage to connected equipment, facilities or products due to a fault of the product, safety measures must be taken before usage, such as the installation of a fuse, an overheating protection device and the like. No warranty is valid in the case of an accident arising from the use of this product without such safety measures.


## $\triangle$ CAUTION

- The $₫$ mark on the plate affixed to the instrument:

On the terminal nameplate affixed to the case of this instrument, the alert mark $\widehat{\Delta}$ is printed. This is to warn you of the risk of electric shock which may result if the charger is touched while being energized.

- As a means to turn the power off, a switch or a breaker should be installed in the external power circuit to be connected to the power terminal of the instrument. Fix the switch or the breaker adjacently to the instrument in a position which allows it to be operated with ease, with an indication that it is a means of turning the power off. Use a switch or a breaker which meets the requirement of IEC60947.
- Fuse:

Since the instrument does not have a built-in fuse, do not forget to install a fuse in the power circuit to be connected to the power terminal. A fuse should be positioned between a switch or a breaker and the instrument and mounted on the $L$ side of the power terminal.

Fuse rating / characteristics: 250 V AC $1 \mathrm{~A} /$ medium lagged or lagged type.
Use a fuse which meets the requirement of IEC60127.

- Voltage / current of a load to be connected to the output terminal and the alarm terminal should be within a rated range.

Otherwise, the temperature will rise to reduce the life of product and/or to result in problems with the product. For rated voltage/current, see " 9 . Specifications" of this manual.
The output terminal should be connected with a device which meets the requirements of IEC61010.

- A voltage / current different from that of the input specification should not be applied to the input terminal.

It may reduce the life of the product and/or result in problems with the product. For rated voltage / current, see " 9 . Specifications" of this manual.

- In the case of voltage or current input, the input terminal should be connected to a device which meets the requirement of IEC61010.
The instrument is provided with a draft hole for heat discharge. Take care to prevent metal and other foreign matters from getting into it. Failure to do so may result in trouble with the instrument or may even cause a fire.
- Don't block the draft hole or allow dust or the like to stick to it. A rise in temperature or insulation failure may result in a reduction of the life of the product and/or problems with it or may cause a fire.
For spaces between installed instruments, refer to "3-3. External Dimensions and Panel Cutout."
- It should be noted that repeated tolerance tests against voltage, noise, surge, etc. may lead to deterioration of the instrument.
- Users are prohibited from remodeling the product or abnormal use of it.
- It takes 30 minutes to display the correct temperature after applying power to the Program Controller. (Therefore, turn the power on more than 30 minutes prior to the operation.)


## 2. Introduction

## 2-1. Check before Use

This product has been fully inspected for quality assurance prior to shipment. Nevertheless, you are requested to make sure that there is no error, damage or shortage of delivered items by checking the model codes and the external view of the product and the number of accessories.
(1) Confirmation of Model Codes

Check the model codes stuck to the case of the product to ascertain if the respective codes designate what were specified when you ordered it, referring to the following code table:

## Example of model codes:



NOTE: For any problem with the product, shortage of accessories or request for information, please contact our sales agent.

## 2-2. Handling Instruction

(1) Don't operate the keys on the front panel with a hard or sharply pointed object. Operate the keys only by softly touching them by your fingertips.
(2) When cleaning the instrument, wipe it gently with a dry cloth. Never use solvent such as a thinner.

## 3. Installation and Wiring

3-1. Installation Site (environmental conditions)

(1) Where flammable gas, corrosive gas, oil mist and particles that can deteriorate electrical insulation are generated or abundant.
(2) Where the temperature is below $-10^{\circ} \mathrm{C}\left(14^{\circ} \mathrm{F}\right)$ or above $50^{\circ} \mathrm{C}\left(122^{\circ} \mathrm{F}\right)$.
(3) Where the relative humidity is above $90 \% \mathrm{RH}$ or below dew point.
(4) Where highly intense vibration or impact is generated or transferred.
(5) Near high voltage power lines or where inductive interference can affect the operation of the instrument.
(6) Where the instrument is exposed to dew drops or direct sunlight.
(7) Where the height is above 2000 m .
(8) Outdoors.
(9) Where the instrument is exposed to the flow of blowing air.

NOTE: The environmental conditions belong to the installation category II of IEC60664 and the degree of pollution is 2 .

## $\triangle$ CAUTION

For safety's sake and to protect the functionality of the product, don't draw out its body from the case. If it needs to be drawn out for replacement or repair, contact our sales agent.
(1) Cut a hole for mounting the controller in the panel by referring to the cutout drawing in Section 3-3.
(2) The panel thickness should be $1.0-4.0 \mathrm{~mm}$.
(3) As the instrument is provided with pawls for fixing, just press it firmly from the front of the panel. The case is fixed to the panel by means of the pawls.
(4) The FP93 is designed as a panel-mounting model. Never use it without mounting on the panel.

## 3-3. External Dimensions and Panel Cutout

## External dimensions




Panel cutout drawing


Unit: mm

## 3-4. Wiring

In wiring operation, close attention should be paid to the following:

## $\triangle$ CAUTION

- Make sure to disconnect this instrument from any power source during wiring operation to prevent an electric shock.
- Be certain that the protective conductor terminal ( $(\underset{)}{ }$ ) is properly grounded. Otherwise, an electric shock may result.
- To prevent an electric shock, don't touch wired terminals and other charged elements while they are being energized.
(1) In wiring operation, follow the terminal layout shown in Section 3-5 and the terminal arrangement in Section 3-6 and make sure to carry out the correct wiring.
(2) Use press-fit terminal which fits an M3.5 screw and has a width of 7 mm or less.
(3) In case of thermocouple input, use a compensating cable compatible with the selected type of thermocouple.
(4) In the case of R.T.D. input, the resistance of a single lead wire must be $5 \Omega$ or less and the three wires must have the same resistance.
(5) The input signal wire must not be accommodated with a high-voltage power cable in the same conduit or duct.
(6) Shield wiring (single point grounding) is effective against static induction noise.
(7) Twisting the input wires at short and equal intervals is effective against electromagnetic induction noise.
(8) In wiring for power supply, use a wire or cable whose performance is equal to or higher than the 600 V vinyl insulated wire having a sectional area of $1 \mathrm{~mm}^{2}$ or larger.
(9) The wire for grounding must have a sectional area of $2 \mathrm{~mm}^{2}$ or larger and must be grounded at a grounding resistance of $100 \Omega$ or less.
(10) Clamp the screws of terminals firmly. Clamping torque: $1.0 \mathrm{~N} \cdot \mathrm{~m}(10 \mathrm{kgf} \cdot \mathrm{cm})$
(11) If the instrument appears to be easily affected by power supply noise, use a noise filter to prevent malfunctioning.
(12) Mount the noise filter on the grounded panel and make wire connection between the noise filter output and the power line terminals of the controller as short as possible.


3-5. Terminal Layout
(Follow the terminal layout and terminal arrangement table shown below in your wiring operation.)

| *1 | TERMINAL |  |  |
| :---: | :---: | :---: | :---: |
| SPECIFICATION | 23 | 24 | 25 |
| RS-232C | SG | SD | RD |
| RS-485 | SG | + | - |






3-6. Terminal Arrangement Table

| Name of terminal | Description / Code | Terminal No. |
| :---: | :---: | :---: |
| Power supply | 100-240V AC/24V AC: L, 24 V DC: + 100-240V AC/24V AC: N, 24V DC: - | $\begin{aligned} & 11 \\ & 12 \\ & \hline \end{aligned}$ |
| Protective conductor | Protective grounding $\left(\frac{1}{*}\right.$ | 13 |
| Input | ```Voltage (V) Current (mA): + R.T.D.: A, thermocouple/Voltage (mV): + R.T.D.: B, thermocouple/Voltage (mV, V), Current (mA): - R.T.D.: B``` | $\begin{array}{\|l\|} \hline 6 \\ 7 \\ 7 \\ 9 \\ 10 \end{array}$ |
| Control output | Contact: COM, SSR drive voltage/Voltage/Current: Contact: NO, SSR drive voltage/Voltage/Current: Contact: NC | $\begin{aligned} & 14 \\ & 15 \\ & 16 \end{aligned}$ |
| Event output | COM <br> EV1 <br> EV2 <br> EV3 | $\begin{aligned} & 17 \\ & 18 \\ & 19 \\ & 20 \\ & \hline \end{aligned}$ |
| Analog output (option) | $+$ | $\begin{array}{\|l} \hline 21 \\ 22 \\ \hline \end{array}$ |
| Communication (option) | SG <br> RS-232C: SD, RS-485: + <br> RS-232C: RD, RS-485:- | $\begin{aligned} & \hline 23 \\ & 24 \\ & 25 \\ & \hline \end{aligned}$ |
| External control input | COM DI1 DI2 DI3 DI4 | $\begin{array}{\|l\|} \hline 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{array}$ |
| Status output (DO) (option) | $\begin{aligned} & \hline \text { COM } \\ & \text { DO1 } \\ & \text { DO2 } \\ & \text { DO3 } \\ & \text { DO4 } \\ & \hline \end{aligned}$ | $\begin{aligned} & 26 \\ & 27 \\ & 28 \\ & 29 \\ & 30 \end{aligned}$ |

NOTE 1: With thermocouple, voltage, or current input, shorting across B and B terminal will cause an error. Leave terminal No. 10 open.
NOTE 2: With voltage ( V ) or current ( mA ) input, don't connect anything with terminal No.7. Any connection with it may cause problems with the instrument.


| Name | Function |
| :---: | :---: |
| (1) Measured value (PV) display | (1) Present measured value is displayed in the screen group 0 . (red) <br> (2) Type of parameter is shown on each parameter screen. |
| (2) Action display | (1) $\nearrow$ (green) Ascending action lamp <br> - Lights while ascending step is in execution. <br> (2) $\longrightarrow$ (green) Level action lamp <br> - Lights while level step is in execution. <br> (3) $\searrow$ (green) Descending action lamp <br> - Lights while descending step is in execution. <br> (4) OUT (green) Control output lamp <br> - Lights when contact or SSR drive voltage output is ON, goes out when output turns OFF. <br> - For current or voltage output, brightness increases or decreases in proportion to output. <br> (5) RUN (green) RUN action lamp <br> - Lights while program is in execution. <br> - Blinks while FIX is in execution. <br> (6) HLD (green) HLD action lamp <br> - Lights when a brief suspension (Hold) is set while program is in execution. <br> (7) GUA (green) GUA action lamp <br> - Lights in case PV value does not reach a set range of deviation values when moving to level step during program execution (guarantee soak). <br> (8) COM (green) Communication action lamp <br> - Lights when COM mode is selected in case the instrument includes the communication option. The lamp does not light if local is selected as communication mode. <br> (9) AT (green) Auto tuning action lamp <br> - Blinks while AT is in execution. The lamp lights during standby for AT and goes out when AT action comes to an end or is terminated. <br> (10) MAN (green) Manual control output action lamp <br> - Blinks when manual control output is selected on output screen. The lamp remains extinct during automatic control output. <br> (11) EV1 (orange) Event 1 output action lamp. Lights when event 1 turns ON. EV2 (orange) Event 2 output action lamp. Lights when event 2 turns ON. EV3 (orange) Event 3 output action lamp. Lights when event 3 turns ON. <br> (12) DO1 (green) Status output 1 action lamp. Lights when status output 1 turns ON. DO2 (green) Status output 2 action lamp. Lights when status output 2 turns ON. DO3 (green) Status output 3 action lamp. Lights when status output 3 turns ON. DO4 (green) Status output 4 action lamp. Lights when status output 4 turns ON. |
| (3) Pattern number display | (1) Pattern No. currently selected is displayed. (green) |
| ④ Step No. Display | (1) Step No. currently in execution is displayed. (green) <br> (2) Step No. currently set in screen group 2 is displayed. <br> (3) PID No. currently set in screen group 4 is displayed. |
| (5) Target set value (SV) display | (1) Target set value is displayed on the basic screen of screen group 0 . (green) <br> (2) Present output value is displayed in $\%$ on the output monitor screen of screen group 0 . <br> (3) Selected item and set value are displayed on each parameter screen. |


| Name | Function |
| :---: | :---: |
| © Operating keys | (1) © (parameter) key <br> - Pressing this key on any screen calls the next screen onto display. <br> - Pressing this key continuously for 3 seconds calls the initial screen of screen group 5 . <br> (2) (up) key <br> - Used to increase a numerical value on a numerical value setting screen. <br> - Used to select an item on an item selection screen. <br> (3) (down) key <br> - Used to decrease a numerical value on a numerical value setting screen. <br> - Used to select an item on an item selection screen. <br> (4) ©NT (entry) key <br> - Used to register a set data changed by means of the or key on each screen (the decimal point of the rightmost digit goes out). <br> - When pressed for 3 seconds continuously on output (OUT) screen, this key switches between automatic output and manual output. <br> (5) ${ }^{\circledR} \mathbb{R}$ (group) key <br> - When pressed in the middle of setting in screen groups $1,3,4$ or 5 , the initial screen of the group is called onto display. <br> - When pressed in the screen group 2 , the initial screen of screen group 1 is called onto display. <br> - When pressed on the basic screen, the display moves to screen group 1 , screen group 3 , screen group 4 and the basic screen in the order mentioned. <br> - When pressed on the initial screen of screen group 5 , the basic screen is called. <br> (6) ©TTD (pattern) key <br> - When pressed during stop (RST) on the basic screen, a starting pattern can be selected. It is registered by pressing the ©NT key <br> - This key is used to move to other screen groups. For details, see Section 5-1 or 5-5. <br> (7) (TTED (step) key <br> - This key is used to move to other screen groups. For details, see Section 5-1 or 5-5. <br> (8) (ress (run/reset) key <br> - When pressed continuously for 3 seconds on the basic screen, execution (RUN) and stop (RST) are switched. <br> - When pressed in any of screen groups $1-5$, the preceding screen is returned onto display. |

## 5. Explanation of Screens and Setting

## 5-1. Parameter Flow

NOTE: Four kinds of frame lines signify the following. The figure on the left of each frame represents screen No.


Screens regularly shown by key operation and other means.


Screens shown when appropriate option is added or selected.


Screens may or may not be shown depending upon setting. $\square$ Screens for monitoring (without automatic return).

(1) How to Move from Screen Group to Screen Group and Explanation of Screen Groups

NOTE 1: To move among screen groups $0,1,3$ and 4 , press the ${ }^{\circledR R P}$ key on the basic screen of screen group 0 or the initial screens of screen group 1,3 or 4 .

NOTE 2: To move between screen groups 0 and 5, pressing the © key for 3 seconds continuously on the basic screen of screen group 0 calls the initial screen of screen group 5 , and pressing the $\mathbb{C R P D}^{\text {key }}$ on the initial screen of screen group 5 calls the basic screen of screen group 0 .

NOTE 3: Pressing the © key in any screen group calls the next screen and pressing it on the last screen of a screen group calls the initial screen.
 of the screen within the frame to a designated screen by pressing that key. (This applies to screen groups $1,2,3,4$ and 5 .)


NOTE 5: The screen group 1 has patterns 1-4. (One pattern has 16 setting screens.) The number of patterns is selectable (which is set on the $5-1$ screen; the initial value is 4 ).

NOTE 6: The screen group 2 has steps 1 to 40 (one step containing three setting screens). The number of steps is selectable (which is set on the $1-2$ screen; the initial value is 10 ).

NOTE 7: The screen group 4 has 6 PID Nos. (Each having 8 setting screens) and Zone PID.
NOTE 8: Within a screen group, you can move from screen to screen by pressing an appropriate key indicated in screen sequences (which are shown in the following page on).


Screen Group 3 FIX-related screen group


Screen Group 4 PID-related screen group



## 5-2. Application of Power and Display of Initial Screen

When power is applied, the initial screen and two screens are displayed successively, each for about 1 second as shown below. Then the basic screen is displayed.

| F993 | Display of model code: FP93 <br>  display |
| :---: | :---: |
| Lᄃ |  |
|  |  |
| Qut | Display of control output Output type ( $\zeta$ ' : Contact, $P:$ : SSR drive voltage, $\boldsymbol{L}^{\prime}:$ : Voltage, $\Sigma^{-}:$Current) display |
| $\square$ |  |
|  | Display of lower limit value of selected measuring range Display of higher limit value of selected measuring range |
|  |  |
|  |  |
|  |  |
|  |  |  |
|  |  |  |

## 5-3. How to Change Screens

(1) How to Change Screen Groups 0-5

- Pressing the $\mathbb{C R}^{(R P)}$ key on the basic screen of screen group 0 calls the initial screen of screen group 1 .
- Pressing the $@$ key on the basic screen of screen group 0 continuously for 3 seconds calls the initial screen of screen group 5 .
- Pressing the key on any screen of screen group 1 calls the 2-1 screen of screen group 2.
- Pressing the ${ }^{6 R P}$ key on the initial screen of screen group 1 calls the initial screen of screen group 3 .
- Pressing the ©RP key on any of the screens of screen group 2 calls the initial screen of screen group 1 .
- Pressing the $\Subset_{\mathbb{R} P}$ key on the initial screen of screen group 3 calls the initial screen of screen group 4 .
- Pressing the ©RP key on the initial screen of screen group 4 calls the basic screen of screen group 0 .
- Pressing the $\Subset$ key on the initial screen of screen group 5 calls the basic screen of screen group 0 .
- Pressing the $\varrho_{\text {GRP }}$ key on any screen midway of screen group $0,1,3,4$ or 5 calls the initial screen of the screen group.

(Nevertheless, to return to the initial screen in screen group 1 or 4 , you have to press the ©RD key or press the © key continuously to move to the last screen of the group before returning to the initial screen.
(1) How to move among 0-4 screen groups

(2) How to move between screen group 0 and screen group 5

(2) How to Change Screen in Screen Group 0

Every time the © key is pressed, the next screen is called, and the basic screen is called from the last screen.

(3) How to Change Screen in Screen Group 3

Every time the (a) key is pressed, the next screen is called, and the basic screen is called from the last screen. Pressing the key calls the preceding screen.

(4) How to Change Set Values (Data)

To change data on a screen which is called by pressing the © key, use the © or $\odot$ key, and register the changed data by pressing the © ©NT) key.

## 5-4. Before Starting Up

To begin with, check the wiring and carry out the following on the respective setting screens. (Factory-set items and items already set by equipment manufacturers need not be set here.)
(1) Checking Wiring
(2) Applying power
(3) Setting Measuring Range
: Apply operating power. The controller is energized and the data display and other lamps light.
: Select a code from the list of measuring range codes on the 5-5 Measuring range code setting screen. For current, voltage or mV input, lower/higher limit values and the position of decimal point of the contents of display in response to input signal should be set.
(Depending on a selected code, selection on the 5-6, 5-7 and 5-8 is also required.)
(4) Setting Control Mode
: In the case of ON-OFF (two-position) action, call the 4-1 Output proportional band setting screen of screen group 4 and select OFF for P and register it.
(5) Setting Control Output Characteristic
: On the 5-12 Control output characteristics setting screen, select either RA (heating action) or DA (cooling action) for Act according to the purpose of use and register it.
(6) Setting Other Data
: Input necessary items such as program, event action and external input of program control. Record necessary data in "8. Record of Parameter Setting" and input them.
(7) Note on Initialization upon Change of Data
: When a set data on measuring range code, input unit, higher/lower limit value of input scaling, event type, analog output type or the like is changed, related data is initialized and resetting is required.

(1) Measured value display (PV display) (2) Target set value display (SV display)
(3) Pattern No. display (PTN display)
(4) Step No. display (STP display)

## $5-5$. Explanation of Screen Group 0 and Setting



(๑) \begin{tabular}{l}

| Initial value of SV: 0.0 or 0 |
| :--- |
| Setting range: Within measuring range | <br>

PV display : Display of measured value (PV) <br>
SV display : Display of target set value (SV) and change of setting <br>
(in FIX mode) <br>
PTN display : Display of pattern No. currently in execution. <br>
STP display : Display of step No. currently in execution. <br>
When the PTN) key is pressed in the state of stop (RST), thedecimal <br>
point of PTN display blinks to enable you to select a start pattern. <br>
Upon selection, press the (NNT) key to register. In the event you do <br>
not register in 3 minutes, the preceding state returns. When (FIX) <br>
mode has been selected, FIX SV value can be changed by means of <br>
the or key. When the key is pressed for 3 seconds <br>
on this screen, RUN is put into execution.
\end{tabular}

## 0-1 Output monitoring screen


(1) Setting HLD Execution

0-5 HLD execution setting screen
 HLD is put in execution when ON is selected and selection of OFF releases it. Upon execution of HLD, PROG execution is stopped temporarily. The HLD lamp lights during the execution of HLD. This screen is on display only when RUN is in execution in the PROG mode. If stop (RST) is input through external control input (DI) 1 or in the case of a change to FIX mode through DI, the $0-0$ basic screen is returned.
In case HO -is is set for external control input (DI), it functions only as an input status monitoring screen. ADV input is not valid during the execution of HLD.
To 0-6 screen
(2) Setting ADV Execution

0-6 ADV execution setting screen


The selection of ON puts ADV in execution. Upon execution of ADV, the step currently in execution is terminated and forced to move to the next step.
This screen is displayed only when RUN is in execution in the
PROG mode. If stop (RST) is input through external control input (DI) 1 or in the case of a change to FIX mode through DI, the $0-0$ basic screen is returned.
In case Fiofiol is set for external control input (DI), it functions only as an input status monitoring screen. ADV is not valid for 1 second upon changing to a new step and for 2 seconds upon execution of ADV.
(3) Setting Auto Tuning (AT) Execution

0-7 AT execution setting screen

(GRP) Initial value: OFF
Setting range: ON/OFF
The selection of ON puts AT in execution and AT is released when OFF is selected. AT execution is possible only when RUN is in execution and the AT lamp blinks during AT execution. The lamp lights during standby.
While AT is in execution, setting and changing are not possible except releasing AT execution, keylock setting, communication mode switching, and RUN/RST, HLD and ADV setting on the basic screen.
For further details, refer to "6-4. Auto Tuning (AT)."
To 0-0 basic screen

## 5-6. Explanation of Screen Group 1 and Setting

1-0 Initial screen (pattern 1)


## 1-1 Start SV setting screen

 limiter makes the four decimal place blinking.

## (2) Setting End Step

1-2 End step setting screen
 The number of steps of a program pattern is set. The number of patterns is set on the 5-1 screen (initial value: 4). The maximum number of steps changes according to the number of patterns.
The number of pattern $=1$ : The maximum number of steps $=40$ The number of pattern $=2$ : The maximum number of steps $=20$ The number of pattern $=4$ : The maximum number of steps $=10$

In case a lower number than the number of step currently in execution is set, the program terminates upon completion of the step currently being executed or moves to the initial step.
（3）Setting Time Signal
1－3 Time signal 1 （TS1）ON step setting screen

（D）

> Initial value: OFF
> Setting range: OFF, $1 \sim$ End step
> A step in which TS1 signal is output is set. This screen is on display when $=\boldsymbol{\sigma} 5$ i (tmS1) is set for event or status output. For details about time signal, refer to " $6-15$ Time Signal." A change of end step makes four decimal places blink if set value of end step $<$ TS1 ON step setting.

1－4 Time signal 1 （TS1）ON time setting screen


1－5 Time signal 1 （TS1）OFF step setting screen

（D）

## （vires）Initial value：OFF Initial value：OFF Setting range：OFF， $1 \sim$ End step

A step in which TS1 signal is stopped is set．This screen is not displayed when TS1 ON step is OFF．A change of end step makes four decimal places blink if set value of end step＜TS1 OFF step setting．

1－6 Time signal 1 （TS1）OFF time setting screen


1－7 Time signal 2 （TS2）ON step setting screen

（D） （H）Ins）Inial value：OFF Setting range：OFF， $1 \sim$ End step
A step in which TS2 signal is output is set．This screen is on display when 上，元ご（tmS2）is set for event or status output For details about time signal，refer to＂6－15 Time Signal．＂A change of end step makes four decimal places blink if set value of end step $<$ TS2 ON step setting．

1－8 Time signal 2 （TS2）ON time setting screen


## （3）5：Initial value： 00.00 <br> Setting range： $00.00 \sim 99.59$

A time from the start of step in which TS2 signal is output to the output of the signal is set．
This screen is not displayed when TS2 ON step is OFF
1－9 Time signal 2 （TS2）OFF step setting screen


[^0]

A time from the start of step in which TS2 signal is stopped to the stop of the signal is set．This screen is not displayed when TS2 OFF step is OFF．For details about time signal，refer to ＂6－15．Time Signal．＂
（4）Setting Event Action Point
1－11 Event 1 （EV1）action point setting screen

 The number of executions of a presently set pattern is set．In case a lower number than the number of pattern currently being executed is set，the program is terminated upon execution to the end step．
（6）Setting PV Start
1－15 PV start setting screen


To 1－16 screen

## 5-8. Explanation of screen Group 3 and Setting

3-0 Initial screen


3-1 FIX mode ON/OFF setting screen


ON/OFF of FIX mode is set. When FIX is selected in setting external control input (DI), this screen is for monitoring only.
(2) Setting FIX SV Value

3-2 FIX SV value setting screen


3-3 FIX No. setting screen


PID No. in FIX mode is selected. This screen is not displayed during the use of zone PID. When 0 is selected, action is carried out as PID No.1.
(4) Setting FIX Event Action Point

3-4 FIX event 1 (EV1) action point setting screen


Outside higher/lower limit deviation values (od) 2000
Within higher/lower limit deviation values (id) 2000 Higher limit absolute value (HA) Higher limit value of measuring range
Lower limit absolute value (LA) Lower limit value of measuring range
Setting range:
Higher limit deviation value or lower limit deviation value $1999 \sim 2000$ digits
Within or outside of higher/lower limit deviations
$0 \sim 2000$ digits
Higher limit absolute value or lower limit absolute value Within measuring range
This screen is displayed when action code $\mathrm{Hd} \sim \mathrm{LA}$ is set for EV1, and action point of set event in FIX mode is set. When any other code than Hd ~ LA is set, the screen is not displayed.

3-5 FIX 2 event 2 (EV2) action point setting screen


3-6 FIX event 3 (EV3) action point setting screen

(ธ) $\uparrow$ The The same as the $3-4$ screen except that EV1 is changed to EV3.

To 3-0 initial screen

5-9. Explanation of screen Group 4 and Setting
Setting of PID Outputs of PID Nos. 1-6
(1) Setting Outputs of PID Nos. 1 - 6


4-1 Output proportional band setting screen


4-2 Output hysteresis setting screen

(ब)


Basically this setting is not necessary when auto tuning is executed.
For integral time, refer to "6-5. PID Action." This screen is not displayed when $\mathrm{P}=\mathrm{OFF}$.

4-4 Output derivative time setting screen

(®) (tus) Initial value: 30
Setting range: OFF, $1 \sim 3600$ seconds
Basically this setting is not necessary when auto tuning isexecuted.
For derivative time, refer to "6-5. PID Action." This screen is not displayed when $\mathrm{P}=\mathrm{OFF}$.

(®) 4 Intial value: 0.40
Setting range: OFF, $0.01-1.00$
A value to be used to suppress overshooting or undershooting in expert PID is set. Setting 1.00 for SF makes overshoot minimum, and when $\mathrm{SF} \leqq 0.10$ in the program mode or $\mathrm{SF}=\mathrm{OFF}$ in the FIX mode, expert PID does not function and ordinary PID action is carried out. This screen is not displayed when $\mathrm{P}=\mathrm{OFF}$.
 to"6-7. Output Lower Limit and Higher Limit Setting Limiters."

To 4-8 screen

4-8 Higher limit output limiter setting screen


To the initial screen of the set one of 4-0 PID Nos. $1 \sim 6$.

(D) (Hys) Initial value: OFF Setting range: ON/OFF
ON/OFF of zone PID is set. For zone PID, refer to "6-9. Zone PID."
4-12 Zone 1 SP setting screen


4-13 Zone 2 SP setting screen


4-14 Zone 3 SP setting screen


## 4-15 Zone hysteresis setting screen



To 4-10 Initial screen of zone PID.

## 5-10. Explanation of Screen Group 5 and Setting

5-0 Initial screen

(1) Setting the Number of Patterns

5-1 The number of patterns setting screen

(()) © Ulas) Initial value: 4 Setting range: $1,2,4$
The number of patters to be used is set. Maximum steps of a pattern changes according to the number of patterns: 40 steps when the number of patterns is 1,20 when it is 2 and 10 when it is 4 . A set number is unable to be changed during RUN in the PROG mode.

(a)
(4) Initial value: $\boldsymbol{H} \boldsymbol{H}$

Setting range: $\boldsymbol{H} \boldsymbol{\sim} \boldsymbol{\sim}(\mathrm{HM}) / \boldsymbol{\sim}$
A unit of time used in various items, such as step signal and step
time, is set.
ifiris stands for "-hours $\sim$ minutes" and

- 5 for "~minutes $\sim$ seconds."

A set unit is unable to be changed during RUN in the PROG mode.
(3) Setting With/Without Power Failure Compensation

5-3 With/without power failure compensation setting screen


## (The Initial value: OFF <br> Setting range: ON/OFF

When OFF is set, the instrument starts up in the state of RST in the PROG mode when power is applied again, that is, a state preceding the power failure is not maintained. When ON is selected, the instrument starts up in a state preceding the power failure. (In the FIX mode, a state preceding the power failure is always maintained.)
The following are excluded, however:

- AT in execution.
- A change in the state of DI input (Power supply is interrupted in the state of ON, turned OFF during interruption).
- PID No. where hysteresis of zone PID is involved.
(4) Setting Input Abnormality Mode

5-4 Input abnormality mode setting screen
 the process of program control, is set.
ifini: The HLD state precedes recovery from scaleover or resetting. Output is fixed to $0 \%$. If the sensor has no problem, the HLD state is released upon applying power again.
 reset is input. (Time continuation) Output is fixed to $0 \%$.
ー上: Program action is released and the instrument is put in the state of reset.
(5) Setting Measuring Range Code

5-5 Measuring range code setting screen


Initial value: 05
Setting range: $01 \sim 92$
A measuring range is set. A table of measuring range codes is shown in " $5-11$. Measuring Range Code Table." A set code is unable to be changed during RUN in the PROG mode.
(6) Setting Input Unit

5-6 Screen for changing set input unit


5-7 Input scaling lower limit value setting screen

(2) © © $\begin{aligned} & \text { Initial value: } 0.0 \\ & \text { Setting range: }-1999 \sim 9989 \text { digits }\end{aligned}$

A lower limit value of scaling for linear input $(\mathrm{mV}, \mathrm{V}, \mathrm{mA})$ is set. During sensor input, the lower limit of measuring range is displayed and no change is possible. A set value is unable to be changed during RUN in the PROG mode.

5-8 Input scaling higher limit value setting screen


Setting range: (Input scale) lower limit value $+10 \sim$ Lower limit value +5000 digits A higher limit value of scaling for linear input $(\mathrm{mV}, \mathrm{V}, \mathrm{mA})$ is set. During sensor input, the higher limit of measuring range is displayed and no change is possible. A set value is unable to be changed during RUN in the PROG mode.
Note: If a lower limit value is set so as to have a difference of less than 10 counts or more than 5000 counts from a higher limit value, the higher limit value is forcibly changed to the lower limit value +10 counts or the lower limit value +5000 .

5-9 Input scaling decimal point position setting


The position of decimal point for input scaling is set. During sensor input, the screen is for monitoring only and no setting is possible. A set position is unable to be changed during RUN in the PROG mode.

## (8) Setting PV Bias

5-10 PV Bias setting screen


Initial value: 0.0
Setting range: -1999~2000 digits
PV bias is used to correct an error of input from sensor or the like. When a bias is set, control is also carried out with a corrected value.

## (9) Setting PV Filter

5-11 PV filter setting screen


Initial value: 0
Setting range: $0 \sim 100$ seconds In case input changes conspicuously or noise continues, PV filter is used to mitigate such undesirable effect. When 0 second is set, filter does not function.
(10) Setting Output Control Characteristic

5-12 Output control characteristic setting screen

|  | FiEt - GRP $\longrightarrow$ To 5-0 screen |
| :---: | :---: |
|  | - -7 |
| (0) | Initial value: $\boldsymbol{r} \boldsymbol{F}$ <br> Setting range:- $-7(R A)$, -8 (DA) <br> A characteristic of control output is set. RA is for heating and DA cooling. <br> (11) Setting Proportional Cycle |

5-13 Propotional

( 3
Initial value: Y output: $30, \mathrm{P}$ output: 3 Setting range: $1 \sim 120$ seconds
Proportional cycling time of control output is set. This screen is not displayed in the case of voltage or current output. For details of proportional cycle, see
"6-8. Proportional Cycle Time."
(12) Setting SV Limiter

5-14 SV limiter lower limit value setting screen

(©) $\uparrow$ Ints Initial value: Lower limit value of measuring range
Setting range: Lower limit value of measuring range ~ Higher limit - 1 count
When a narrower range than the measuring range is used for target value setting, a lower limit value is set. (It prevents erroneous setting in a dangerous range.)

To 5-15 screen

5－15 SV limiter higher limit value setting screen

（Q）
RHITs．Initial value：Higher limit value of measuring range Setting range： $\mathbf{5}$ ， measuring range
When a wider range than the measuring range is used for target value setting，a higher limit value is set．（It prevents erroneous setting in a dangerous range．）
Note：In SV limiter setting，SV limiter lower limit value $<$ SV limiter higher limit value and the lower limit value is given preference，that is，it is not possible to set a higher value which is less than a lower level +1 count．
（13）Setting External Control Input
5－16 External control input 2 （DI2）action code setting screen


## （Q）


An action code of external control input 2 （DI2）is set．For details of DI input，see＂6－10．External Control Input．＂This screen does now show 5だロ
Table of External Control Input（DI）Codes

| DI code | Description |
| :---: | :---: |
| M， 019 | Without DI |
| $\mathrm{BiO}_{6} \mathrm{i}$－i | Hold |
| 5 Cof | Advance |
| 51 | FIX level |
|  | Starting pattern No． 2 bit |
|  | Starting pattern No． 3 bit |

5－17 External control input 3 （DI3）action code setting screen
首：（SPT2）

An action code of external control input 3 （DI3）is set．This screen is not displayed when the external control input 2 （DI2） code is $5 \boldsymbol{5} \boldsymbol{F} \boldsymbol{Z}$
This screen does not show気荡。
5－18 External control input 4 （DI4）action code setting screen


An action code of external control input 4 （DI4）is set．This screen is not displayed when the external control input 2 （DI2） code is $5 \boldsymbol{E}$ ．and when the external control input 3 （DI3） code is $5 \%$

（14）Setting Events
5－19 Event 1 （EV1）type setting screen

（ब）
（wiss）Initial value： Hi －i

The type of event to be set as EV1 is selected from the following table．

To 5－20 screen

Table of Event Type Codes

| Code | Type of event |
| :---: | :---: |
|  | None |
| － $\mathrm{B}_{6}$ | Higher limit deviation |
| isiof | Lower limit deviation |
| 日㫛 | Outside higher／lower limit deviations |
| －－ | Within higher／lower limit deviations |
| i－ition | Higher limit absolute value |
| ； | Lower limit absolute value |
| 50 | Scaleover |
| Brion | Hold |
| Coide | Guarantee soak |
| 66！ | Time signal 1 |
|  | Time signal 2 |
| －－ 19 | RUN status |
|  | Step signal |
| Ersit | End signal |
| $\mathrm{FO}_{5} \mathrm{~F}_{1}$ | FIX |

5－20 Event 1 （EV1）hysteresis setting screen

（©） 4 （2ys）Initial value： 5 Measuring range： $1 \sim 999$ digits Hysteresis is set for EV1．This screen is displayed when an EV1

5－21 Event 1 （EV1）standby action setting screen

（D）
（21）R5 In Initial value： 1 Measuring range： $1 \sim 4$
EV1 standby action type code is selected from the following table．This screen is displayed when an EV1 code is $\boldsymbol{i - f} \boldsymbol{- 1}$ ， $\therefore \therefore$ 日

Table of Standby Action Codes

| Code | Description |
| :---: | :--- |
| $\boldsymbol{i}$ | Without standby function |
| $\mathbf{\Xi}$ | Standby action only when power is applied，or when <br> the state is switched from RST（stop）to RUN <br> （execution） |
| $\mathbf{z i}$ | Standby action when power is applied，or when the <br> state is switched from RST（stop）to RUN <br> （execution），or when SV in execution is changed |
| $\mathbf{- i}$ | Control mode（without standby） |

5－22 Event 2 （EV2）type setting screen


To 5－26 screen

5－26 Event 3 （EV3）hysteresis setting screen

（D）$\uparrow$ Intial value： 5 Setting range： $1 \sim 999$ digits
The explanation on 5－20 screen applies to this screen except EV1 changed to EV3．

5－27 Event 3 （EV3）standby action code setting screen

（D）（5）Initial value： 1 Setting range： $1 \sim 4$ The same as the 5－21 screen EV1 changed to EV3．
（15）Setting Status Output（DO）
5－28 Status output 1 （DO1）action code setting screen


5－29 Status output 2 （DO2）action code setting screen
（ORP）To 5－0 screen

5－30 Status output 3 （DO3）action code setting screen


5－32 Status output type setting screen


5－33 Analog output scaling lower limit setting screen

（2）Twiss Initial value：The lower limit value of setting range for PV and SV，and 0.0 for OUT
Setting range：Within measuring range when PV or SV is selected and $0.0 \sim 100.0 \%$ when OUT is selected．
A minimum value $(0 \mathrm{mV}, 4 \mathrm{~mA}$ or 0 V$)$ of analog output signal is set at a value intended to be output as the lower limit value of scaling．
To 5－34 screen

5－34 Analog output scaling higher limit setting screen

\＆Initial value：The higher limit value of setting
Setting range：Within measuring range when PV or SV is selected and $0.0 \sim 100.0 \%$ when OUT is selected．
A minimum value $(10 \mathrm{mV}, 20 \mathrm{~mA}$ or 10 V$)$ of analog output signal is set at a value intended to be output as the higher limit value of scaling．

Inversed scaling of Ao＿L $>$ Ao＿H is also possible．
In the case of Ao＿L＜Ao＿H In the case of Ao＿L＞Ao＿H

（17）Setting Communication
Note：For communication，refer to the Communication Interface Instruction Manual provided separately．
5－35 Communication mode setting screen
$\longrightarrow$ To 5-0 screen
(())

> The following selections can be made for communications. In COM 1 mode, change from LOC to COM by key operation is possible.
> When COM 2 mode is selected, change from LOC to COM by key operation is impossible

5－36 Communication protocol Setting

```
\(\longrightarrow\) GRP）To 5－0 screen
Ehis
（D）
```

```
\[
\begin{aligned}
& \text { ー上, (RTU) }
\end{aligned}
\]
```

Shim：Shimaden standard mode asc：MODBUS ASCII mode rtu：MODBUS RTU mode Select either one of the communication protocols．

5－37 Communication address setting screen


5－38 Communication speed setting screen

（3）Initial value： 1200
Setting range： $1200,2400,4800,9600,19200 \mathrm{bps}$ The speed of communication is set．
Note 1：Because of a limited number of digits， 19200 bps is

Note 2：Special keys on the communication speed screen： When the（FTN key and the（ITEP key are pressed simultaneously for 3 seconds on this screen，the present speed is forcibly changed．This interrupts communication and the mode is changed from communication to local． To restart communication，the same speed as that of the host has to be set．

To 5－39 screen

| 5－39 ¢ $\downarrow^{\text {¢ }}$ |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |
| －GRP $\longrightarrow$ To 5－0 screen |  |  |  |  |  |  |
| TE |  |  |  |  |  |  |
| Initial value：7E1 <br> Setting range： 8 types in the following table <br> A communication data format is set． |  |  |  |  |  |  |
| Selection | Data length | Parity | Stop <br> bits | Shimaden standard | MODBUS／ ASCII mode | MODBUS／ RTU mode |
| 7E | 7 bits | EVEN | 1bit | $\bigcirc$ | $\bigcirc$ | － |
| TEE | 7 bits | EVEN | 2bit | $\bigcirc$ | $\bigcirc$ | － |
| 791 | 7 bits | None | 1bit | $\bigcirc$ | $\bigcirc$ | － |
|  | 7 bits | None | 2bit | $\bigcirc$ | $\bigcirc$ | － |
| EE | 8 bits | EVEN | 1bit | $\bigcirc$ | － | $\bigcirc$ |
| EEE | 8 bits | EVEN | 2bit | $\bigcirc$ | － | $\bigcirc$ |
| Eir | 8 bits | None | 1bit | $\bigcirc$ | － | $\bigcirc$ |
| EMロ | 8 bits | None | 2 bit | $\bigcirc$ | － | $\bigcirc$ |

5－40 Start character setting screen

（D）
4 （ Ins In
Setting range：51（STX），R上（＠）
Which of STX and＠is used as the start character of communication format is set．

5－41 BCC ${ }^{\star}$ operation type setting screen

|  | EE | GRP $\longrightarrow$ To 5－0 screen |
| :---: | :---: | :---: |
| （D） | $\begin{aligned} & \text { Initial va } \\ & \text { Setting r } \\ & \text { An operation } \\ & \text { the following } \end{aligned}$ | ue： 1 <br> nge： $1 \sim 4$ <br> pe for error detection BBC check is selected from able： |
|  | Type of Operation | Description |
|  | i | Add operation from start character to text end character |
|  | $\square$ | 2＇s complement after add operation from start character to text end character |
|  | 3 | Exclusive OR operation from 2nd character to text end character |
|  | 4 | Without BCC operation |

5－42 Communication delay time setting screen

（D）
4 Whes Initial value： 20 Setting range： $1 \sim 100$
Minimum delay time lag from receiving a communication
command to transmission is set
Minimum delay time $=$ Set value $\times 0.512 \mathrm{msec}$
5－43 Communication memory mode setting screen
$\longrightarrow$ GRP To 5－0 screen
E
（®）
－（ruxs Initial value：EE Setting range：$E=\boldsymbol{F}, \boldsymbol{F}$
Which of EEPROM and RAM data is written in through communication is set．

| Type | Writing Process |
| :---: | :---: |
| $E E \%$ | All to be written in EEPROM |
| － $77 \%$ | All to be written in RAM |
| F．E | FIX SV，OUT and STEP SV to be written in RAM and others in EEPROM |

＊Note on the RAM mode selected as communication mode：Since all are written in RAM，setting inconsistency may arise in some case For details，refer to＂6－17．Notes on RAM as Communication Memory Mode．＂

To 5－44 screen

## 5－44 Communication mode type setting screen

```
GRP }\longrightarrow\mathrm{ To 5-0 screen
G日G
```

（whas）Initial value：COM1
Setting range：COM1，COM2
Selects type of communication mode． Set to COM1 if you want to enable key operation while writing by communication．

| Communication mode types | COM1 |  | COM2 |  |
| :--- | :---: | :---: | :---: | :---: |
| Communication mode | COM | LOC | COM | LOC |
| Key operation | Available | Available | Not available | Available |
| Communication writing | Available | Available | Available | Not available |

（18）Setting Keylock
5－45 Keylock setting screen

（D）

## $\left\lvert\, \uparrow \begin{aligned} & \text { Initial value：OFF } \\ & \\ & \text { Setting range：OFF，1，2，} 3\end{aligned}\right.$

Items which should not be changed are locked．Data are unable to be changed on locked screens．Select OFF to release the lock．

| Lock No． | Range to be locked |
| :---: | :---: |
| GFF | Release of lock（All data allowed to be changed．） |
| ； | Keylock of the screen groups 3， 4 and 5 （excluding communication mode and special keys on communication speed screen） |
| E＇ | Keylock of screen groups 1，2，3， 4 and 5 （excluding communication mode and special keys on communication speed screen） |
| 3 | Keylock of all screens excluding RUN／RST on the basic screen，communication mode screen and special keys on communication speed screen） |

To 5－0 Initial screen

## $5-11$ ．Measuring Range Codes Table

Select a measuring range from the following table．
Note：A change of a measuring range code will initialize all data related to the measuring range．

| Input type |  | Code | Measuring range |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | ${ }^{\circ} \mathrm{C}$ | ${ }^{\circ} \mathrm{F}$ |
|  | B ${ }^{1} 1$ |  | Fif | $0 \sim 1800$ | 0～3300 |
|  | R | 8 | $0 \sim 1700$ | 0～3100 |
|  | S | 8 | $0 \sim 1700$ | 0～3100 |
|  | K | 7－9＊2 | $-199.9 \sim 400.0$ | $-300 \sim 750$ |
|  |  | 75 | $0.0 \sim 800.0$ | $0 \sim 1500$ |
|  |  | 65 | $0 \sim 1200$ | 0～2200 |
|  | E | 67 | $0 \sim 700$ | $0 \sim 1300$ |
|  | J | 78 | $0 \sim 600$ | $0 \sim 1100$ |
|  | T | 75＊2 | －199．9～ 200.0 | $-300 \sim 400$ |
|  | N | 17 | $0 \sim 1300$ | $0 \sim 2300$ |
|  | PL II＊3 | 1 i | $0 \sim 1300$ | $0 \sim 2300$ |
|  | WRe5－26＊4 | 10 | $0 \sim 2300$ | $0 \sim 4200$ |
|  | U＊5 | \％＊2 | $-199.9 \sim 200.0$ | $-300 \sim 400$ |
|  | L＊5 | $1 \%$ | $0 \sim 600$ | $0 \sim 1100$ |
|  | Pt | 71 | $-200 \sim 600$ | $-300 \sim 1100$ |
|  |  | $70^{7}$ | $-100.0 \sim 100.0$ | $-150.0 \sim 200.0$ |
|  |  | － 7 | $-50.0 \sim 50.0$ | －50．0～120．0 |
|  |  | 79 | $0.0 \sim 200.0$ | $0.0 \sim 400.0$ |
|  | JPt | － 9 | $-200 \sim 500$ | $-300 \sim 1000$ |
|  |  | 85 | $-100.0 \sim 100.0$ | －150．0～200．0 |
|  |  | $37 \%$ | $-50.0 \sim 50.0$ | －50．0～120．0 |
|  |  | 36 | $0.0 \sim 200.0$ | $0.0 \sim 400.0$ |
|  | $-10 \sim 10 \mathrm{mV}$ | 71 | Scaling possible． <br> Setting range：$-1999 \sim 9999$ <br> Span： $10 \sim 5000$ <br> Decimal point position： $0.000 \sim$ None |  |
|  | $0 \sim 10 \mathrm{mV}$ | 7 |  |  |
|  | $0 \sim 20 \mathrm{mV}$ | 77 |  |  |
|  | $0 \sim 50 \mathrm{mV}$ | 74 |  |  |
|  | $10 \sim 50 \mathrm{mV}$ | 75 |  |  |
|  | $0 \sim 100 \mathrm{mV}$ | 75 |  |  |
|  | －1～ 1 V | 81 |  |  |
|  | $0 \sim 1 \mathrm{~V}$ | 8 |  |  |
|  | $0 \sim 2 \mathrm{~V}$ | E\％ |  |  |
|  | $0 \sim 5 \mathrm{~V}$ | 86 |  |  |
|  | $1 \sim 5 \mathrm{~V}$ | 6 |  |  |
|  | $0 \sim 10 \mathrm{~V}$ | E\％ |  |  |
| mA | $0 \sim 20 \mathrm{~mA}$ | 91 |  |  |
|  | $4 \sim 20 \mathrm{~mA}$ | 8 |  |  |

Thermocouple B，R，S，K，E，J，T，N：JIS／IEC
R．T．D Pt100：JIS／IEC；JPt100：Former JIS
＊1 Thermocouple B：Accuracy guarantee not applicable to $400^{\circ} \mathrm{C}\left(725^{\circ} \mathrm{F}\right)$ and below．
＊2 Thermocouple K，T，U：Accuracy of those whose readings are below $-100^{\circ} \mathrm{C}$ is $\pm 0.7 \% \mathrm{FS}$ ．
＊3 Thermocouple PLII：Platinel
＊4 Thermocouple WRe 5－26：A product of Hoskins
＊5 Thermocouple U，L：DIN 43710
When not designated，factory－set measuring range is K thermocouple $\left(0.0 \sim 800.0^{\circ} \mathrm{C}\right)$ ．

## 6 Operation and Functions

6-1. Using FIX Mode
FIX: Adjustment function without using the program function.
(1) Pressing the or (■ey on the 3-1 FIX ON/OFF screen turns OFF shown on the target value (SV) display to ON and the decirnal point of the rightmost digit blinks. Then, press the ©NT) ENT key, and the decimal point stops blinking to register the selection. (When OFF is set for FIX on this screen, the program mode turns ON.)
(2) Pressing the (2) key calls the next setting screen. Set a necessary item, if any.
(3) When the display returns to the basic screen upon completion of setting, $F$ is shown on the pattern number display and the FIX mode is ON.


6-2. Setting Target Value (SV) (FIX Mode)
(1) Setting on the basic screen

When the or key is pressed on the $0-0$ basic screen, the decimal point of the rightmost digit blinks and the numerical value changes. The value keeps changing while either of the keys is being pressed. Once an intended value is reached, press the ENT key to register it. The registration of the data stops the blink of the decimal point.
(2) Setting on the SV setting screen

When the or key is pressed on the 3-2 FIX SV setting screen, the decimal point of the rightmost digit blinks and the numerical value changes. The value keeps changing while either of the keys is being pressed. Once an intended value is reached, press the ENT key to register it. The registration of the data stops the blink of the decimal point.

* In the program mode, SV value is unable to be changed on the basic screen.
* In the program mode, the 1-1 start SV setting screen and the 2-1 step SV setting screen should be used to set an SV.
* No target value can be changed while auto tuning (AT) is in execution. It should be set after releasing AT.

Example: Setting target value at $100^{\circ} \mathrm{C}$
0-0 Basic screen


## 6-3. Setting Output Manually


During manual output, the MAN lamp lights and it goes out when automatic output begins.
To set a target value, press the $\triangle$ or key on the output monitoring screen. When the target value is reached, the setting completes. To release it, press the ENT key again for 3 seconds continuously, and automatic output is resumed.

* Changing to manual output is not possible while auto tuning is in execution.
(1) $100 \%$ output is shown as $\quad 999$ and the decimal point of ${ }^{\circ}$ blinks.
(2) When OFF is set for proportional band (P) in the case of contact output or SSR drive voltage output, the value of output is either $0.0 \%$ or $100.0 \%$.
(3) When OFF is set for proportional band $(\mathrm{P})$ in the case of voltage output or current output, the output value becomes the lower or higher limit value of a set output limiter.


## 0-1 Output monitoring screen


(4) Supplementary Explanation of Monitoring Screen

The output monitoring screen (OUT) and automatic output/manual output:

1) When auto is changed to manual, output is in balanceless action and an output value immediately before the change is displayed. When manual is changed to auto, output is in bumpless action if it is bumpless. If it is outside the proportional band, however, the output is not in bumpless action.
2) In case power supply was turned OFF and power is applied again, control output is in the mode (either manual or auto) which was ON at the time of interruption of power supply.
NOTE: Even in the manual mode, it is possible to call another screen but it should be noted that control output is in the manual state. Blinking of the MAN action LED shows that the manual mode is ON.

### 6.4. Auto Tuning (AT)

This is the function to automatically calculate and set P.I.D. values, i.e., parameters of PID control. The time required for calculation depends on the details of control.
(1) Execution of AT

Pressing the key on the AT execution setting screen changes OFF shown on the target set value (SV) display to ON and the decimal point on the rightmost digit blinks. Upon pressing the ©®N key, the decimal point stops blinking and AT action begins. When the target set value stays in the inclined portions (portions indicated by the arrows of the action display), AT is in the state of standby (the AT lamp lights), and AT is executed while the target set value stays in the level portion (the AT lamp blinks).
While AT is in execution, the ON/OFF action of output is repeated several times in accordance with rise and fall of the measured value from the target value as the border and PID values are stored in an internal memory. Immediately when they are stored, control using these PID values begins and AT action ends. Then, the target set value display shows OFF and the AT lamp goes out. (In case there is AT still to be executed, it is put in the state of standby.)

# AT in execution 


2) Release of AT in the Middle

To release AT in the middle, select OFF on the AT execution setting screen by the use of $\checkmark$ key and press the (ENT) key.

## NOTE: In case AT is released in the middle, PID values are not changed.

(3) Reasons Why AT Does Not Function

1) Control output is in manual mode.
2) The proportional band ( P ) of control output is OFF.
3) $P V$ value (measured value) is in the state of scaleover.
4) On the keylock screen, No. 3 is selected. (AT is executed when it is turned ON before keylock setting.)
5) $A T$ is suspended (RST).
(4) If the following conditions arise while AT is in execution, AT is released:
6) Output is at $0 \%$ or $100 \%$ continuously for 200 minutes.
7) $P V$ value gets scaleover
8) RST input is received.
9) AT is terminated by key operation or through communication.
10) AT of PID No. 1 through No. 6 (No. 3 in the case of zone) has completed.

## 6-5. PID Action

(1) P (Proportional action)

The ratio (\%) of a range in which control output changes relatively to a measuring range is set. Output increases or decreases in proportion to difference between PV value and SV value. The narrower the proportional band, the larger a change in output, i.e., the stronger the proportional action. Nonetheless, an excessively narrow proportional band causes control to vibrate, resulting in control similar to ON-OFF action.
(2) I (Integral time)

This is the function to correct an offset (constant deviation) produced in proportional band. The longer the integral time, the weaker the correcting action, that is, reducing the integral time strengthens the correcting action but it may cause undulation of control results due to integral hunting.
(3) D (Derivative time)

A change in control output is estimated and overshooting is suppressed to improve the stability of control. A longer derivative time strengthens derivative action but it may cause control results to vibrate.

## 6-6. Manual Reset

In PID action, an offset is corrected automatically by I, i.e., integration. When OFF is set for I, however, this correction is not carried out and so output is increased or decreased manually for correction. This method is called manual reset.

## 6-7. Output Lower Limit and Higher Limit Setting Limiters

(1) Output limiter means to limit a minimum or maximum value of control output and this function is effective in securing the lowest temperature or suppressing overshooting of control.
(2) Output limiter gives preference to a lower limit value. When a larger lower limit value than a higher limit value is set, the higher limit value is forced to become the lower limit value $+0.1 \%$. In other words, it is not possible to set a higher limit value which is less than a lower limit $+0.1 \%$.

## 6-8. Proportional Cycle Time

It can be set within a range from 1 to 120 seconds in the case of contact output or SSR drive voltage output. Proportional cycle time is ON time +OFF time within a proportional band.

## 6-9. Zone PID

The PID control of this instrument allows you to select and set the zone method.
In the zone PID control, a measuring range is divided into three types maximum, and control is carried out with PID No. which is selected automatically from an SV value set for each step.
Its basic action is: PID No. changes when control output becomes larger than an SP value or smaller than a zone hysteresis. An example of its action is diagramed below.


When above diagram shows SV as: Below $200^{\circ} \mathrm{C} \rightarrow$ Action with PID No. 1
$200^{\circ} \mathrm{C} \sim 300^{\circ} \mathrm{C} \rightarrow$ Action with PID No. 2
Above $300^{\circ} \mathrm{C} \rightarrow$ Action with PID No. 3

When the setting of zone SP is changed as follows:

> Zone 3 SP: $100^{\circ} \mathrm{C}$ Below $200^{\circ} \mathrm{C} \rightarrow$ Action with PID No. 3
> Zone $1 \mathrm{SP}: 200^{\circ} \mathrm{C} 200^{\circ} \mathrm{C} \sim 300^{\circ} \mathrm{C} \rightarrow$ Action with PID No. 1
> Zone $2 \mathrm{SP}: 300^{\circ} \mathrm{C}$ Above $300^{\circ} \mathrm{C} \rightarrow$ Action with PID No. 2

* When the same zone SP value is set, the lowest number is used preferentially.
* Even when a zone SP value in action is changed within a zone hysteresis, PID No. is not changed as long as output remains within the hysteresis.


## 6-10. External Control Input (DI)

The instrument has four DIs. DI is caused to function when any other item than non is set on the setting screen and external terminals are shorted. Action caused by each setting is described below:
(1) RUN/RST

Switching between RUN and RST. As this is assigned to DI1 fixedly, the setting is unable to be changed. Being edge input, RUN and RST are switched by shorting across terminals 1 and 2 .
(2) ADV

As on the 0-6 ADV execution screen, when executed, the present step comes to an end and is forced to proceed to the next step. Being edge input, ADV is executed every shorting across terminals.

## (3) HLD

As on the $0-5$ HLD execution screen, when executed, the present step time is temporarily suspended and SV is fixed. Being level input, shorting across terminal puts HLD in execution and opening releases it. A change in step time, step SV, time signal ON/OFF time, etc. does not take effect until HLD is released.
(4) FIX

As on the 3-1 FIX mode ON/OFF setting screen, when executed, the FIX mode turns ON. Being level input, shorting across terminals turns the FIX mode ON and opening releases it.
(5) SPT3

A pattern No. at the start of program action is selected by 3 bits of DI2 - DI4.
(6) SPT2

A pattern No. at the start of program action is selected by 2 bits of DI3 and DI4. Being level input, shorting across terminals produces " 1 " and opening " 0 ". Since the time for removing chattering of level input is
125 msec , edge input action need to remain ON for 125 msec or longer. If a number exceeding the number of patterns is input, a maximum number of patterns allowed to be set can be set.
For example: Where the number of patterns $=2$ and DI input is 011 , the number of start pattern is 2 .

| S | DI4, 3, 2 |  |
| :---: | :---: | :---: |
|  | $0 \begin{array}{lll}0 & 0 & 0\end{array}$ | Start with pattern 1 |
|  | 0 | Start with pattern 1 |
|  | 0 1 10 | Start with pattern 2 |
|  | $0 \begin{array}{lll}0 & 1 & 1\end{array}$ | Start with pattern 3 |
|  | $1 \begin{array}{lll} \\ 1 & 0 & 0\end{array}$ | Start with pattern 4 |
|  | 01 | Start with pattern 4 |
|  | 11 | Start with pattern 4 |
| SPT2 | DI4, 3 |  |
|  | 0 0 | Start with pattern 1 |
|  | 0 | Start with pattern 1 |
|  | 10 | Start with pattern 2 |
|  | 1 | Start with pattern 3 |
|  | Not possible | Start with pattern 4 |

（1）Deviation Alarm
An alarm action point is set by a deviation of measured value（PV）from target set value（SV）．
For instance，to activate an alarm when measured value（PV）reaches $30^{\circ} \mathrm{C}$ against SV value at $20^{\circ} \mathrm{C}$ ，higher limit deviation alarm is set at $10^{\circ} \mathrm{C}$ ．To activate alarm when measured value（PV）lowers below $30^{\circ} \mathrm{C}$ in the case of an SV value at $100^{\circ} \mathrm{C}$ ， lower limit deviation alarm is set at $-70^{\circ} \mathrm{C}$ ．This function is convenient for an alarm action point to follow deviations from target set value．The set range is $-1999-2000$ digits．
（2）Absolute Value Alarm
An alarm point is set by an absolute value．
For instance，to activate an alarm when measured value exceeds $50{ }^{\circ} \mathrm{C}$ ，higher absolute value alarm is set at $50{ }^{\circ} \mathrm{C}$ ．To activate an alarm when measured value lowers below $20^{\circ} \mathrm{C}$ ，lower absolute value alarm is set at $20^{\circ} \mathrm{C}$ ．Setting of higher or lower absolute value alarm is possible as long as it is within the measuring range．
（3）Standby Action
In case 2 or 3 is set for event standby action，there is no event output upon applying power（or changing set value，or switching stop（RST）to execution（RUN））even when measured value is within an event action area（an ON area）．Event is output when it reaches the event action area again after it gets out of the event action area（gets in an OFF area）．
（4）Non－standby Action
In case event standby action is set for 1 and 4，an alarm is output when measured value gets in an action area upon applying power（or changing target set value）．
（5）Control Mode（4 is set for standby action）
No event is output at the time of scaleover．The same applies to event standby．
6－12．Setting Event Standby Action On 5－21 Event 1 standby action code setting screen
（1）When event output is used as an alarm，select from 1,2 and 3 of the standby action code table．
（2）When event output is used for control，set 4 （control mode）．In case 4 is selected，however，event output turns OFF at the time of input abnormality．
（3）When 2 is selected，standby action functions only when power is applied．
（4）When 3 is selected，standby action functions when power is applied and when SV in execution is changed．
（5）When changed to 1 or 4 while standby action is going on，the standby action is released immediately．
（6）Even when 2 or 3 is selected as standby action，it has no effect if PV value is outside the ON area of event action when power is applied or SV is changed．

6－13．Diagrams of Alarm Actions Selectable as Event
Diagrams of alarm actions to be selected for event 1－3 are shown below：
$\triangle: S V$ value $\boldsymbol{\Delta}$ ：Set value of alarm action point



L－d＇：Inside higher／lower limit deviations alarm


HR ：Higher limit absolute value alarm


LR ：Lower limit absolute value alarm Action ON


## 6－14．Event and Status Output Actions

The following nine items can be set for status output of＂5－28，5－29，5－30 and 5－31＂as well as events：


HoLd Hold ：To be output while HLD is set on DI input and 0－5 HLD execution setting and in communication in the PROG mode．
ELRE Guarantee soak ：To be output while the state of guarantee remains in the PROG mode．
Ł̄̄5 ：Time signal 1 ：To be output in the ON／OFF condition set in the time signal 1 setting（1－3，1－4，1－5 and 1－6）in the PROG mode．For details，see 6－15．
とームコ Time signal 2 ：To be output in the ON／OFF condition set in the time signal 2 setting（1－7，1－8，1－9 and 1－10）in the PROG mode．For details，see 6－15．
run RUN status
SLPS Step signal
EndS End signal
：To be output while RUN action is in execution．
：To be output for one second when a step proceeds to another in the PROG mode． ：To be output for one second when the last step ends in the PROG mode．
：To be output while RUN action is in execution in the FIX mode．

Time signal: Event output and status output can be produced for a designated period of time. Two points per pattern are equipped and ON step, OFF step, ON time and OFF time can be set individually.
(1) Time signal functions under the following conditions:

1) $\llcorner\bar{n} 5$; or $\llcorner\bar{n} 5 己$ is set as status output of event output.
2) OFF is not selected in Time signal ON step setting.
3) ON time is set within the end step.
4) In the total length of time elapsed since the start of program, ON time $\leqq$ OFF time.

- In the case of ON step $=$ OFF step and ON time $=$ OFF time, time signal turns ON for one second.
- In the case of ON step $<$ OFF step and ON time $=$ OFF time in the total length of time elapsed since the start of program, time signal turns ON for one second.
(Example of setting: 1 step 10 minutes, ON step $=1$, ON time 15 minutes, OFF step $=2$ and OFF time 5 minutes)

* When a time signal-related parameter is changed during Hold (HLD), the change is not reflected until HLD is released.
${ }^{(2)}$ Reasons why time signal does not function (always OFF) (Time signal does not function in the following cases):

1) $\llcorner\bar{n} 5$; or $\llcorner\bar{n} 5 己$ is not set as status output of event output (including the case where these options are not added).
2) OFF is selected as Time signal ON step setting.
3) ON time exceeds the end step.
4) In the total length of time elapsed since the start of program, ON time $>$ OFF time is set.
(3) Other Matters related to Setting
5) The time of time signal is stopped during HLD and guarantee soak.
6) In case ON step and ON time are set and OFF step is OFF, once time signal turns ON, the end step also turns ON. (When one or more program executions are set, both remain ON until they are completed.)
7) In case OFF time is set beyond the end step, the end step is forcibly turned OFF. When ON step is the first step and 00:00 is set for ON time, it does not turn OFF.
8) In case ON time equals step time, it turns ON at the start of the next step.

| Other examples of setting |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| ON time > end step <br> (time signal not effective) |  | Step 1 | Step 2 | Step 3 |  |
|  |  |  |  |  |  |
| ON step $=$ OFF only ON step is <br> effective (remains ON until the <br> program completes.) |  |  |  |  |  |
| OFF time > end step <br> (forcibly turned OFF at the end <br> step.) |  |  |  |  |  |

5) When TS is assigned to a step of which the step time is 0 , the action is the same as TS is assigned to the next step.

6-16. Status (DO) Output
This instrument has four status output as optional function (open collector output) points.


## 6-17. Auto Retum Function

Should there be no key operation for 3 minutes on each screen except the monitoring screens (adjustment output, remaining time of step, the number of pattern executions, PID No.), the display returns automatically to the 0-0 basic screen of screen group 0 (auto return).

## 6-18. Notes on RAM as Communication Memory Mode

In case RAM is selected on the 5-42 communication memory mode, all set data are written in RAM. Care should be taken as this causes nonconformity of set data in a pattern like the following:
On the assumption that input range is $05\left(\mathrm{~K} 0.0-800.0{ }^{\circ} \mathrm{C}\right)$,
${ }^{(1)}$ An event code is changed from higher limit deviation value to higher limit absolute value through communication (this change is recorded in RAM).
(2) Communication mode is changed from COM to LO(.
(3) Event action point setting is changed from 800.0 to 700.0 by key operation. (Being in LOC mode, this change is recorded in EEPROM).
(4) Power supply is interrupted and power is applied agan.
(5) The event code recorded in RAM is cleared and highr limit deviation value is read from EEPROM.
(6) Since the event action point set as 700.0 has been wren in EEPROM, 700.0 is read.
(7) Consequently, although the setting range of higher liit deviation value is actually -1999-2000 digits, an impossible value of 7000 digits is set.
To ensure proper use of the instrument, correct data nust be set again.

## 7. Error Codes, Causes and Remedies

| Screen display | Problem | Cause | Remedy |
| :---: | :---: | :---: | :---: |
| Hini-i-i <br> (HHHH) | Higher limit side scaleover | (1) Break of thermocouple input wiring <br> (2) Break of R.T.D. input A wiring <br> (3) Input measured value exceeded higher limit of measuring range by more than $10 \%$. | ${ }^{(1)}$ Check thermocouple input wiring. If wiring has no problem, check and replace thermocouple. <br> (2) Check wire connection to R.T.D. terminal A. If wiring has no problem, replace R.T.D. <br> (3) For voltage or current input, check the transmitting unit of measured values. Check if set code of measuring range is the same as that of input signal. |
| $i_{(L L E L)}^{1:}$ | Lower limit side scaleover | (1) Problem with wiring connection for input signal <br> (2) Input measured value fell from lower limit of measuring range by $10 \%$ <br> (3) Nonconformity of input range with input signal | (1) Check wire connection for input signal. <br> (2) Check wiring of inversed polarity or break of wiring for measured value input. <br> (3) Check input range and input signal. |
| $\underset{(b----)}{b--}$ | Break of R.T.D. input wiring | (1) Break of B <br> (2) More than one break of A , $B$ and $B$ | Check R.T.D. input terminals $A, A$ and $B$ for breaks. If wiring has no problem, check and replace R.T.D. |
| EABi-1 (CJHH) | Higher limit side scaleover of cold junction (CJ) of thermocouple input | Ambient temperature of FP93 has exceeded $80^{\circ} \mathrm{C}$. | (1) Reduce ambient temperature to the level provided in the environment conditions. <br> (2) In case ambient temperature has not exceeded $80^{\circ} \mathrm{C}$, examine the instrument. |
|  (CJLL) | Lower limit side scaleover of cold junction (CJ) of thermocouple input | Ambient temperature of instrument has fallen to $-20^{\circ} \mathrm{C}$ or lower. | (1) Raise ambient temperature to the level provided in the environment conditions. (2) In case ambient temperature has not fallen to $-20^{\circ} \mathrm{C}$, examine the instrument. |

Note: When you find something wrong with the instrument, please re-read the instruction manual and examine the instrument again. For any problem with the product or further information, please contact our sales agent.

## 8．Record of Parameter Setting

（For convenience sake，recording set values and selected items is recommended．）The initial values are of Code 05 （K）．

| Screen No． | Parameter（Item）／Screen |  | Initial value | Setting／Selection | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0－0 | Basic screen | 0 （ | $\square$ |  |  |
| 0－1 | Output monitor |  | ， |  |  |
| 0－2 | Step remaining time | － | ， |  |  |
| 0－3 | Pattern execution number monitor | ， | － |  |  |
| 0－4 | PID No．monitor | ， |  |  |  |
| 0－5 | HLD execution setting |  | AFF |  |  |
| 0－6 | ADV execution setting | AdV．（ $B$－it） | aFF |  |  |
| 0－7 | AT execution setting | At．（ Ft （ ） | OFF |  |  |
|  |  |  |  |  |  |
| 1－0 | Initial screen | ProG．（Fration | SEE |  |  |
| 1－1 | Start SV | S＿SV．（5－5日） | $\square$ |  |  |
| 1－2 | End step | EStP．（EStF） | 96 |  |  |
| 1－3 | TS1 ON step assignment | t1oS．（Etas） | QF\％ |  |  |
| 1－4 | TS1 ON time | t1ot．（上iot） | 500000 |  |  |
| 1－5 | TS1 OFF step assignment | t1FS．（E1F5） | GF\％ |  |  |
| 1－6 | TS1 OFF time | t1Ft．（E：F！） | 5000 |  |  |
| 1－7 | TS2 ON step assignment | t20S．（Eシロら） | QFF |  |  |
| 1－8 | TS2 ON time | t2ot．（Eロロー） | 8080808 |  |  |
| 1－9 | TS2 OFF step assignment | t2FS．（ | af： |  |  |
| 1－10 | TS2 OFF time | t2Ft．（Eズロ | Eter |  |  |
| 1－11 | EV1 level value <br> $\star * *$ includes action type． | E1＊＊．（E i＊＊） | Hd： 2000 digit <br> Ld：－1999 digit |  |  |
| 1－12 | EV2 level value <br> $\star * * i n c l u d e s ~ a c t i o n ~ t y p e . ~$ | E2＊＊． ®®＊＊＊$^{*}$ | od： 2000 digit id： 2000 digit HA：Higher limit of |  |  |
| 1－13 | EV3 level value $\star * *$ includes action type． | E3＊＊．（Eシ＊＊） | measuring range LA：Lower limit of measuring range |  |  |
| 1－14 | Pattern execution number | Pcnt．（Fにのに） | $i$ |  |  |
| 1－15 | PV start | PV＿S．（F－ES） | AFF |  |  |
| 1－16 | Guarantee soak zone | GUAZ．（ 6 回里三） | GFF |  |  |
|  |  |  |  |  |  |
| 2－1 | Step SV | SV．（ 5 －i） | $\square$ |  |  |
| 2－2 | Step time | tim．（ |  |  |  |
| 2－3 | PID No． |  | $\square$ |  |  |
|  |  |  |  |  |  |
| 3－0 | Initial screen | FiX．（F゙「） | SEE |  |  |
| 3－1 | FIX ON／OFF | FiX．$\left(F_{-5} \square_{6}\right)$ | QFF |  |  |
| 3－2 | FIX SV value setting | F＿SV．（F．S日i） | $\square$ |  |  |
| 3－3 | FIX PID No．setting | FPid．（FFO日） | 8 |  |  |
| 3－4 | EV1 level value <br> ＊＊＊includes action type． | E1＊＊．（E i＊＊） | Hd： 2000 digit <br> Ld：－1999 digit |  |  |
| 3－5 | EV2 level value <br> $\star * *$ includes action type． | E2＊＊． E®＊＊＊$^{\text {a }}$ | od： 2000 digit id： 2000 digit HA：Higher limit of |  |  |
| 3－6 | EV3 level value <br> ＊＊＊includes action type． | E3＊＊．（Eシ＊＊） | measuring range LA：Lower limit of measuring range |  |  |
|  |  |  |  |  |  |
| PID No． 1 |  |  |  |  |  |
| 4－0 | Initial screen | Pid．（ 0 － | SEt |  |  |
| 4－1 | PID P | P．（ $F$ ） | 3.6 |  |  |
| 4－2 | PID hysteresis | dF．（ $-1 ;$ ） | 20 digit |  |  |
| 4－3 | PID I | l．（ $\boldsymbol{l}$ ） | O\％ |  |  |
| 4－4 | PID D |  | 36 |  |  |
| 4－5 | PID MR | mr．（ O ， | 0.6 |  |  |
| 4－6 | PID SF | SF．（ SF） |  |  |  |
| 4－7 | PID lower limit |  | 6.6 |  |  |
| 4－8 | PID higher limit |  | 4080.0 |  |  |
|  |  |  |  |  |  |


| Screen No． | Parameter（Item）／Screen |  | Initial value | Setting／Selection | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: |
| PID No． 2 |  |  |  |  |  |
| 4－0 | Initial screen | Pid．（ $\boldsymbol{P}_{\text {O－G }}$ ） | SE： |  |  |
| 4－1 | PID P | P．（F） |  |  |  |
| 4－2 | PID hysteresis | dF．（ $\boldsymbol{O}$ | 20 digit |  |  |
| 4－3 | PID I | I．（ $\mathrm{l}^{\text {d }}$ ） | 908 |  |  |
| 4－4 | PID D | d．（ $\mathrm{sig}^{\text {）}}$ | 38 |  |  |
| 4－5 | PID MR | mr．（ | 0.6 |  |  |
| 4－6 | PID SF | SF．（ ¢F） | 70．408 |  |  |
| 4－7 | PID lower limit |  | 0.6 |  |  |
| 4－8 | PID higher limit | O＿H．（ $\mathrm{O}-\mathrm{H}$ ） | 68080.6 |  |  |
| PID No． 3 |  |  |  |  |  |
| 4－0 | Initial screen |  | 55 |  |  |
| 4－1 | PID P | P．（ $F$ ） | $3: 6$ |  |  |
| 4－2 | PID hysteresis |  | 20 digit |  |  |
| 4－3 | PID I | I．（ $\boldsymbol{\prime}$ ） | 908 |  |  |
| 4－4 | PID D | d．（ $\quad$ ） | 30 |  |  |
| 4－5 | PID MR | mr．（ O ， | 9.9 |  |  |
| 4－6 | PID SF | SF．（ 5\％） | C2， 6 |  |  |
| 4－7 | PID lower limit | O＿L．（ atb） |  |  |  |
| 4－8 | PID higher limit | O＿H．（a，H） | 86080.6 |  |  |
| PID No． 4 |  |  |  |  |  |
| 4－0 | Initial screen | Pid．（ $\boldsymbol{F}_{0}^{-0}$ ） | SEt |  |  |
| 4－1 | PID P | P．（F） | Fib |  |  |
| 4－2 | PID hysteresis | dF．（ | 20 digit |  |  |
| 4－3 | PID I | I．（ ；） | 908 |  |  |
| 4－4 | PID D |  | 36 |  |  |
| 4－5 | PID MR | mr．（ $\overline{\text { ®r }}$ ） | 0 |  |  |
| 4－6 | PID SF | SF．（SF） | 50 |  |  |
| 4－7 | PID lower limit |  | E1．01 |  |  |
| 4－8 | PID higher limit |  | 68080.6 |  |  |
| PID No． 5 |  |  |  |  |  |
| 4－0 | Initial screen |  | $5 E 5$ |  |  |
| 4－1 | PID P | P．（ $F$ ） | 3.0 |  |  |
| 4－2 | PID hysteresis | dF．（ GF） | 20 digit |  |  |
| 4－3 | PID I | I．（ ；） | 988 |  |  |
| 4－4 | PID D | d．（ $\quad$ ） | 30 |  |  |
| 4－5 | PID MR | mr．（ $\boldsymbol{\square}$ ， | 0.6 |  |  |
| 4－6 | PID SF | SF．（ ¢F） | 50 |  |  |
| 4－7 | PID lower limit |  | 0.6 |  |  |
| 4－8 | PID higher limit | O＿H．（a， $\mathrm{Hi}_{\text {）}}$ | 88080.6 |  |  |
| PID No． 6 |  |  |  |  |  |
| 4－0 | Initial screen |  | SEt |  |  |
| 4－1 | PID P | P．（F） |  |  |  |
| 4－2 | PID hysteresis | dF．（ | 20 digit |  |  |
| 4－3 | PID I | I．（ ${ }^{\text {d }}$ ） | 908 |  |  |
| 4－4 | PID D | d．（ $\quad$ i） | 37 |  |  |
| 4－5 | PID MR |  | 0.6 |  |  |
| 4－6 | PID SF | SF．（5F） | 80 |  |  |
| 4－7 | PID lower limit | O＿L．（ ati ） | 96 |  |  |
| 4－8 | PID higher limit | O＿H．（ $\mathrm{O}, \mathrm{H}$ ） | 86080.6 |  |  |
| Zone PID |  |  |  |  |  |
| 4－10 | Initial screen |  | SE： |  |  |
| 4－11 | Zone ON／OFF | ZonE．（ BamE ） | QFF |  |  |
| 4－12 | Zone 1 SP | Z1SP．（ | 0 digit |  |  |
| 4－13 | Zone 2 SP | Z2SP．（ ここの） | 0 digit |  |  |
| 4－14 | Zone 3 SP | Z3SP．（ $\bar{\square} 5$ F） | 0 digit |  |  |
| 4－15 | Zone hysteresis | ZHYS．（ 5 HES） | 20 digit |  |  |
|  |  |  |  |  |  |


| Screen No． | Parameter（Item）／Screen |  | Initial value | Setting／Selection | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 5－0 | Initial screen | init．（5ローt） | SE： |  |  |
| 5－1 | Pattern No．designation | Ptn．（Fロにの） | 4 |  |  |
| 5－2 | Time designation | tmUn．（Eらibiol） | －i\％ |  |  |
| 5－3 | With／without power failure compensation | SAVE．（5Fbe） | GFF |  |  |
| 5－4 | Input abnormality code | So．（ 5 日） | Hisi |  |  |
| 5－5 | Measuring range | rAnG．（ -Fi | 8 |  |  |
| 5－6 | Input unit |  | E |  |  |
| 5－7 | Input scale lower limit value | Sc＿L．（5ロ．${ }^{\text {a }}$ ） | 0.6 |  |  |
| 5－8 | Input scale higher limit value | Sc＿H．（ Sc，i－i） | 4080.6 |  |  |
| 5－9 | Input scale decimal point | ScdP．（ SEGF） | 0.6 |  |  |
| 5－10 | PV bias | PV＿b．（F－b－b） | 0 digit |  |  |
| 5－11 | PV filter | PV＿F．（FE－F） | $\square$ |  |  |
| 5－12 | Output control characteristics | Act．（ $\quad$ 发处） | － 7 |  |  |
| 5－13 | Proportional cycle |  |  |  |  |
| 5－14 | Lower limit value of SV setting | SV＿L．（5bit） |  |  |  |
| 5－15 | Higher limit value of SV setting | SV＿H．（ Sbiriol | E00．0 |  |  |
| 5－16 | External control input 2 code | di2c．（ Giビ心） | 19010 |  |  |
| 5－17 | External control input 3 code |  | $060 \%$ |  |  |
| 5－18 | External control input 4 code |  | 06010 |  |  |
| 5－19 | EV1 action type | E1＿m．（Ei．$\overline{\text { I }}$ ） | － 5 －i |  |  |
| 5－20 | EV1 hysteresis | E1＿d．（Ei． $\boldsymbol{i}$ ） | 5 digit |  |  |
| 5－21 | EV1 standby setting | E1＿i．（E ¢－－） | 1 |  |  |
| 5－22 | EV2 action type | E2＿m．（Eシース） | 1－： |  |  |
| 5－23 | EV2 hysteresis | E2＿d．（E゙ー日） | 5 digit |  |  |
| 5－24 | EV2 standby setting | E2＿i．（E゙ーシ） | 1 |  |  |
| 5－25 | EV3 action type | E3＿m．（EZ－ | －ぃった |  |  |
| 5－26 | EV3 hysteresis | E3＿d．（Eシー | 5 digit |  |  |
| 5－27 | EV3 standby setting | E3＿i．（Eシュロ） | $i$ |  |  |
| 5－28 | Status output 1 code | do1c．（ -10 Co） | 000 |  |  |
| 5－29 | Status output 2 code | do2c．（大ロージヒ） | 19010 |  |  |
| 5－30 | Status output 3 code |  | 19010 |  |  |
| 5－31 | Status output 4 code | do4c．（－ibte） | 9010 |  |  |
| 5－32 | Analog output type |  | $F$ |  |  |
| 5－33 | Analog output scale lower limit |  | 0.0 |  |  |
| 5－34 | Analog output scale higher limit |  | E00 0 |  |  |
| 5－35 | Communication mode | comm．（ | 10E |  |  |
| 5－36 | Communication protocol | Prot（r，ot） | 565 |  |  |
| 5－37 | Communication address |  | 1 |  |  |
| 5－38 | Communication speed | bPS．（ 6 Fra） | 9808 |  |  |
| 5－39 | Communication data format |  | TE： |  |  |
| 5－40 | Start character | SchA．（ SEbin） | 56 |  |  |
| 5－41 | BCC operation | bcc．（ $\quad$ に，） | ； |  |  |
| 5－42 | Delay time |  | $\therefore$ |  |  |
| 5－43 | Communication memory mode | mEm．（ | EEF |  |  |
| 5－44 | Communication mode type |  | に日采 |  |  |
| 5－45 | Keylock |  | GF： |  |  |
|  |  |  |  |  |  |
|  |  |  |  |  |  |
|  |  |  |  |  |  |
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| Pattern No. | 90 |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| Start SV |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  | 80 |  |  |  |  |  |  |  |  |  |  |
| The number of steps |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| TS1 ON step |  |  |  |  |  |  |  |  |  |  |  |
|  | 70 |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| TS1 ON time |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| TS1 OFF step | 60 |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| TS1 OFF time |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  | 50 |  |  |  |  |  |  |  |  |  |  |
| TS2 ON step |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| TS2 ON time |  |  |  |  |  |  |  |  |  |  |  |
|  | 40 |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| TS2 OFF step |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| TS2 OFF time | 30 |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| EV1 setting |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  | 20 |  |  |  |  |  |  |  |  |  |  |
| EV2 setting |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| EV3 setting |  |  |  |  |  |  |  |  |  |  |  |
|  | 10 |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| The number of pattern executions |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| Guarantee soak | 0 |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| PV start |  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |  |
| Step No. |  | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| SV (set value) |  |  |  |  |  |  |  |  |  |  |  |
| Time |  |  |  |  |  |  |  |  |  |  |  |
| PID No. (0~6) |  |  |  |  |  |  |  |  |  |  |  |


| PID No. | 1 | 2 | 3 | 4 | 5 | 6 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $P$ |  |  |  |  |  |  |
| I |  |  |  |  |  |  |
| D |  |  |  |  |  |  |
| Hysteresis |  |  |  |  |  |  |
| MR |  |  |  |  |  |  |
| Target value function |  |  |  |  |  |  |
| Higher limit of output limiter |  |  |  |  |  |  |
| Lower limit of output limiter |  |  |  |  |  |  |


| Zone PID |  |
| :--- | :--- |
| Zone PID ON/OFF |  |
| Zone 1 SP |  |
| Zone 2 SP |  |
| Zone 3 SP |  |
| Zone hysteresis |  |

$\star$ Copy these pages for your use as occasion demands.

## 9. Specifications

- Display
- Display means

Digital display : PV
: SV
: PTN
: STEP
Status display : OUT
: EV1-3 (3 points)
: AT

- MAN

Green LED lamp indication
: DO1-4 (4 points) Green LED lamp indication
: GUA Green LED lamp indication
$:$ RUN Green LED lamp indication (blinks during FIX)
: HLD Green LED lamp indication
: $\nearrow$ "ascend" Green LED lamp indication
$: \rightarrow$ "level" Green LED lamp indication
: 〉 "descend" Green LED lamp indication

- Display accuracy
- Display accuracy maintaining range : $23^{\circ} \mathrm{C} \pm 5^{\circ} \mathrm{C}$
- Display resolution
- Measured value display range
- Display updating cycle
- Input scaling
- Setting
- Local Setting
- SV setting range
- Setting limiter
- Keylock
- Setting of unit
- Input
- Type of input
- Thermocouple
- R.T.D.
- Voltage
- Current
- Sampling cycle
- PV filter
- PV bias
- Isolation
- Control
- Control mode
- Type of control output/rating
- Resolution
- Accuracy of output
- Control output

Proportional band (P) : OFF or 0.1-999.9\% FS (ON-OFF action by OFF)
Integral time (I) : OFF or 1-6000 seconds (P or PD action by OFF)
Derivative time (D) : OFF or 1-3600 seconds (P or PI action by OFF)
Target value function : OFF or $0.01-1.00$
ON/OFF hysteresis : 1-999 digits
Manual reset $: \pm 50.0 \%$ (Effective when I = OFF)

| Output limiter | $:$ Lower limit $0.0-99.9 \%$, higher limit $0.1-100.0 \%$ |
| :--- | :--- |
| Proportional cycle | $: 1-120$ seconds (when contact and SSR drive voltage output) |
| Manual control | $: 0.0-100.0 \%$ Setting resolution 0.1 |
|  | $:$ RA/DA to be set by front key |
|  | $:$ Contact output insulated from all |
|  | AO (analog output) not insulated from SSR drive voltage, current or voltage output but insulated |
|  | from others |

- External control input (DI)
- Number of input points
- Type of input
- Input rating
- Input holding time
- Isolation
- Action input
: 4
: Edge or level input (none, RUN/RST, HLD, ADV, FIX and start pattern No.)
DI1 fixed to RUN/RST for DI2 - 4, selectable from none, RUN/RST, HLD, ADV, FIX and start pattern No.
: Voltage 5 V DC ( $0.5 \mathrm{~mA} / 1$ input)
: Minimum 0.125 seconds
: Not insulated from input and system but insulated from others.
: No-voltage contact or open collector
- Event output
- Contact output rating
: Normal open (1a x 3 common) 240V AC 1A (resistive load)
- Action
- Hysteresis
: ON-OFF action
- Types
: 1-999 digits (during alarm output)
: Selectable from the following 16 types respectively for EV1, EV2 and EV3
No selection, Higher limit deviation, Lower limit deviation, Outside higher/lower limit deviations, Within higher/lower limit deviations, Higher limit absolute value, Lower limit absolute value, Scaleover, Hold, Guarantee soak, Time signal (2 types), RUN status, step signal, End signal, FIX
- Event setting range

Absolute value alarm : Within measuring range
Deviation alarm : Higher limit deviation-1999-2000 digits, lower limit deviation-1999-2000 digits
Outside higher/lower limit deviations: 0-2000 digits
Within higher/lower limit deviations : 0-2000 digits

- Standby action
- Output updating cycle
- Isolation
- Communication function (option)
- Type of communication
- Communication system
- Synchronization system
- Communication distance
- Communication address
- Communication speed
- Communication delay
- Communication memory mode
- Communication protocol
: Selectable from the following 4 types respectively for EV1, EV2 and EV3
: None, Standby 1 (standby only when power is applied), Standby 2 (standby when power is applied, when SV in execution is changed, or when switching RST to RUN) and Standby 3
(input abnormality not output [Control mode])
: 0.25 second
: Insulated from other inputs
: RS-232C or RS-485
: RS-232C/3-line type half duplex system, RS-485/2-line type half duplex multi-drop (bus) system
: Start-stop synchronization system
: RS-232C/Max. 15m, RS-485/Max. 500 m (depending on conditions)
: 1-255
: 1200, 2400, 4800, 9600, 19200 bps
: 1-100 ( $0.512 \mathrm{msec} / \mathrm{unit}$ )
: Selectable from EEP, rAm and r_E
: Shimaden standard mode
Data format $\quad: 7 \mathrm{E} 1,7 \mathrm{E} 2,7 \mathrm{~N} 1,7 \mathrm{~N} 2,8 \mathrm{E} 1,8 \mathrm{E} 2,8 \mathrm{~N} 1,8 \mathrm{~N} 2$
Control code : STX_ETX_CR, STX_ETX_CRLF, @_:CR
Checksum (BCC) : Add, Add two's cmp, XOR, None
Communication data : ASCII data
: MODBUS ASCII mode
Data format : 7E1, 7E2, 7N1, 7N2
Control code : CRLF
Checksum (BCC) : LRC check
Communication data : ASCII data
Function code $: 03 \mathrm{H}, 06 \mathrm{H}$
1)03H Reading of data

2) 06 H Writing of data
: MODBUS RTU mode
Data format $\quad: 8 \mathrm{E} 1,8 \mathrm{E} 2,8 \mathrm{~N} 1,8 \mathrm{~N} 2$
Control code : NON
Checksum (BCC) : CRC-16
Communication data : Binary data
Function code $: 03 \mathrm{H}, 06 \mathrm{H}$
1)03H Reading of data
3) 06 H Writing of data
: Selectable from COM1 and COM2.
: 1 for RS-232C, 31 for RS-485 (Address setting 1-255)
: insulated from other inputs and outputs
: Start character and BCC operation method also selectable

- Analog output (option)
- Number of output points
- Type of analog output
- Output specification/rating
- Output accuracy
- Scaling
- Output resolution
- Output updating cycle
- Isolation
- Status output (DO) (option)
- Number of output points
- Type of output
- Output specification/rating
- Output updating cycle
- Isolation
: 4
: None, scaleover, hold, guarantee soak, time signal (2 types), RUN status, step signal, end signal, FIX
: Open collector darlington output, voltage 24 V DC (maximum load current 20 mA ), saturation voltage during status output ON 1.2 V
: 0.25 second
: Insulated from other inputs and outputs


## - Program

- Number of patterns : Maximum 4 (setting 1,2 or 4 possible)
- Number of steps
: Maximum 10-40 (Total number of steps $=40)$
- Number of PID types
- Number of zone PID types
- Zone hysteresis

Maximum 6
: Maximum 3
: $0-999$ digits

- Time setting
: 0 hour 0 minute -99 hours 59 minutes or 0 minute 0 second -99 minutes 59 seconds/ 1 step
: 1 minute or 1 second
: $\pm$ (set time $\times 0.02 \%+0.25$ second)
: SV, step time and PID No.
: 2 outputs/pattern, to be set within time setting range
Acting for each ste
- Number of pattern executions : Maximum 9999
- PV start : ON/OFF
- Guarantee soak : OFF, 1-999 digits
- Hold : Front key input or external control input
- Advance : Front key input or external control input
- Power failure compensation
: ON/OFF (guarantee not applicable to the period of time of step in which power failure occurs)
- General specification
- Data storage : Non-volatile memory (EEPROM)
- Environmental conditions for instrument operation:

| Temperature | $:-10-50{ }^{\circ} \mathrm{C}$ |
| :--- | :--- |
| Humidity | $: 90 \% \mathrm{RH}$ or less (no dew condensation) |
| Height | $: 2000 \mathrm{~m}$ from the sea level or lower |
| Category | $:$ II |
| Degree of pollution | $: 2$ |

- Storage temperature $\quad:-20-65^{\circ} \mathrm{C}$
- Supply voltage : $100-240 \mathrm{~V} \mathrm{AC} \pm 10 \% 50 / 60 \mathrm{~Hz}$

24 V AC/DC $\pm 10 \%$ (option)

- Input/noise removal ratio
: 50 dB or higher in normal mode $(50 / 60 \mathrm{~Hz})$
130 dB or higher in common mode $(50 / 60 \mathrm{~Hz})$
- Insulation resistance : Between input/output terminals and power terminal 500 V DC $20 \mathrm{M} \Omega$ or above

Between input/output terminals and protective conductor terminal 500 V DC $20 \mathrm{M} \Omega$ or above

- Dielectric strength : Between input/output terminals and power terminal $3000 \mathrm{~V} \mathrm{AC} /$ minute

Between power terminal and protective conductor terminal 1500 V AC/minute
: 16VA maximum for AC, 7 W for DC

- Power consumption
- Conformity with standards

Safety: IEC61010-1 and EN61010-1
IEC61010-2-030 and EN61010-2-030
EMC : EN61326-1

- Protective structure
: Only front panel has dust-proof and drip-proof structure equivalent to IP66. (Panel thickness :1.2-3.2mm)
- Material of case
: PPE(equivalent to UL94V-1)
- External dimensions
: H96 $\times$ W96 $\times$ D111mm (Panel depth: 100 mm )
- Panel thickness
: $1.0-4.0 \mathrm{~mm}$
- Mounting dimensions
: H92 × W92mm
- Weight
: Approximately 450 g


## 产品中有毒有害物质或元素的名称及含量

| 部件名称 | 有毒有害物质或元素 |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 铅（Pb） | 汞（Hg） | 镉（Cd） | $\begin{array}{\|c\|} \hline \text { 六价铬 } \\ (\mathrm{Cr}(\mathrm{VI}) \mathrm{O} \end{array}$ | 多溴联苯 （PBB） | 多溴二苯醚 （PBDE） |
| 印制电路板 | $\times$ | $\bigcirc$ | 0 | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |
| 电子元器件 | $\times$ | 0 | 0 | 0 | 0 | 0 |
| 接线端子 | $\bigcirc$ | 0 | 0 | 0 | 0 | $\bigcirc$ |
| 外壳 | $\bigcirc$ | 0 | $\bigcirc$ | 0 | 0 | $\bigcirc$ |

O：表示该有毒有害物质在该部件所有均质材料中的含量均在SJ／T 11363－2006标准规定的限量要求以下。
$\times$ ：表示该有毒有害物质至少在该部件的某一均质材料中的含量超出 $\mathbf{S J} / \mathrm{T}$ 11363－2006 标准规定的限量要求。

## Temperature and Humidity Control Specialists

 SMMMADEN CO．，LTD．
[^0]:    To 1－10 screen

